

## RC1500A

# Antenna Controller for Single Axis Antennas



#### **FEATURES**

- ➤ Polarization Control Interface Automatic or manual polarization control for three-wire Polarotor<sup>TM</sup> or optional control for 24V rotating feeds with potentiometer feedback
- High-Resolution Pulse Sensor Interface Ensures accurate Ku-band positioning
- Software Controlled Limits
  Provides backup to mechanical limits
- Dual Speed For fast slewing, fine positioning, user programmable

- RS-422 PC Control Interface Automated control with many popular packages; basic PC-control software is Included
- ➤ Adapti-Drive<sup>TM</sup>
  Maintains stable speed with varying load
- Solid-State Drive Circuitry
   Provides reliable, quiet operation, rated for 36V at 10A with over-current protection
- Multi-Band Operation Supports C, Ku and L-band satellites

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#### **OPERATIONAL OVERVIEW**

The RC1500 was designed to provide years of reliable operation through the use of a heavy duty solid-state drive network coupled with a novel microcontroller-based fault monitoring system. The 10 amp rated drive output capability is adequate for either moving feed trackers or full-size linear actuators and the Adapti-Drive digital servo speed control optimizes antenna movement for today's demanding Ku-band applications. Additional features like an RS-422 communications port for PC control and a very user-friendly, menu scheme make the RC1500 a unique and highly adaptable piece of equipment. Overall, the RC1500 is well equipped to handle the demanding requirements for cost sensitive domestic and optionally international inclined-orbit satellite tracking.

#### **MODES**

The RC2000A operates in a mode architecture whereby the controller's operational status is governed by the selected mode. An explanation of these modes are listed below.

MANUAL: Allows for manual jogging of the azimuth and polarization axis. The fast/slow speed toggle is active in this mode.

AUTO: A satellite, previously saved in memory, can be recalled and the RC1500A will position the antenna on the selected satellite.

SETUP: This mode stores values memory for a selected satellite.

RESET: Used to reset the drive over-current protection circuits after the load error has been corrected.

DELETE: Allows the user to delete a satellite from the list of stored values.

FIX: Used to restore the proper position counters in the event of a memory error or sensor failure.

AZIM SLOW: This mode allows the user to select an appropriate drive slow speed value to optimize system performance.

CONFIG: Provides a concise point to enter any necessary system constants or enable options.

LIMITS: Software limits are set for the main axis. This is used as a backup for mechanical limits.

### **SPECIFICATIONS**

| PHYSICAL     |                              |
|--------------|------------------------------|
| Size:        | 19.0" x 3.5" x 9.0" (rack)   |
| Weight:      | 8.5 lbs.                     |
| Temperature: | 0° – 50° C                   |
| Input Power: | 115/230 VAC, 50/60 Hz., 40 W |

| DRIVE         |  |
|---------------|--|
| Output:       | 36 VDC, 10.0 Amps; 360VA   |
| Sensor Input: | Pulse-type: Reed, Hall Effect, Optical   |
| Polarization: | Standard Polarotor <sup>™</sup> Interface,<br>optional rotating Feed-drive at<br>voltages from 5 – 36 VDC @ 1A max |